

Operation, Data Acquisition and
Control System for Dynamometers

MEIDEN

MEIDACS DY6000P Series

100 μ s control response



Empower for new days

100 μ s control response

by **MEIDACS DY6000P Series**



MEIDACS DY6000P Series

Features

High-speed control More than 50 times the control speed of conventional versions.

Version		Control Period
Conventional system	5000P	5ms
New system	6000P	100 μ s

PowerPC for the main Computer The dynamometer is controlled at high accuracy.

Compact-PCI bus for the measurement and control unit Control response has been improved.

MATLAB/Simulink technology The control software quality has been improved.

CAN Interface Noiseless and multi-channel measuring.

Windows 7 Security and stability have been improved.

Database The database manages testing conditions and results.

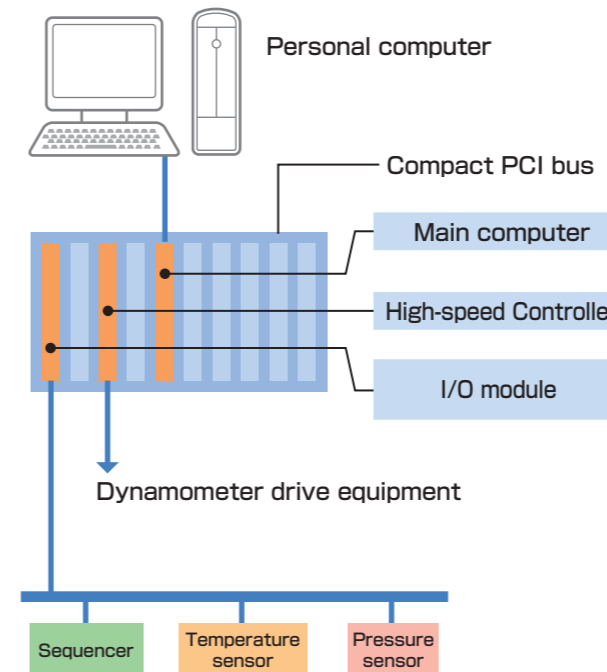


- Simulation of engine and vehicle characteristics can be carried out at high accuracy.
- Vehicle simulation operation can be carried out at the engine bench.
- The continuous forward/reverse operation and the disturbance torque control are available .

Applications

- Engine bench
- Chassis dynamometer
- Power train tester
- Heavy duty engine transient test bench
- Drive train tester with the engine simulation

System configuration



Operation / display computer	Personal computer (OS: Windows 7)	
Main computer board	Processor	MPC7410 500MHz or above 512MB or above memory
	Serial interface	RS-232-C: 2ch
Controller board	Processor	MPC8572E or above Operation at 1.5GHz
	Memory	Flash: 512kB for system boot SDRAM: 2GB Dual port RAM: 1MB
	Optical communication interface	5ch 1.5Mbps
Measurement and control unit	Pulse input(FD)	4ch/board Frequency input range:1 ~ 128kHz
	Analog input(AD)(1)	Isolated 16bit AD 16ch/board
	Analog input(AD)(2)	Isolated 12bit AD 32ch/board
	Analog output(DA)	Isolated 14bit DA
	Digital I/O(D I/O)	Input: 64 points/board Output: 64 points/board
	CAN	1ch
	GPB	1ch

Examples of screens

■ Road load setup screen



■ Monitoring screen



Software specifications

Item	Major functions		
Testing condition setup	<ul style="list-style-type: none"> Parameter data, upper/lower limits supervisory conditions, operation patterns, correlation supervisory conditions, average measurement conditions, high-speed measurement conditions, continuous measurement conditions Options: Max./Min. measurements (Used in average measurement mode) 		
Automatic operation patterns	<ul style="list-style-type: none"> Maximum number of pattern repetitions: 999,999 times Maximum number of pattern composing characters: 1200 characters (60 characters × 20 lines) Maximum number of modes established: 200 modes Maximum number of steps established: 500 steps/mode Step-up conditions: Time [9999.9 sec, min], distance [999.999m], measurement data, external trigger, synchronism with the end of average measurement Digital output: 16 status points Max., 16 pulse points Max. Output timing: Step head (at the execution start of the step), end-of-ramp time (at the end of ramp time), after the specified time (after the lapse of specified time measured from the step head), at the time of step-up 		
Measurement condition setup	Average measurement	High-speed measurement	Continuous measurement
Measurement starting conditions	START button	Start button, measurement items (threshold value upper, lower, up skip, low skip, width)	
Measurement ending conditions	STOP button	Stop button, measurement items (threshold value upper, lower, up skip, low skip, width)	
Measurement items	<ul style="list-style-type: none"> General measurement data Calculated data Special instrument data 	Maximum 100 items from general measurement data and calculated data	General measurement data and calculated data
Measurement period	0.1 sec	1 ~ 999 ms	0.1 ~ 99.9 sec
Max. measuring times	8,000,000 times / Number of measurement items	400,000 times / Number of measurement items	50,000 times
	However, the maximum number of measurements shall be 50,000 times per measurement item.		
Number of data files	1 file/test	Maximum 999 files/test	1 file/test
Upper/lower limits supervision	<ul style="list-style-type: none"> Supervised items: General measurement data and calculated data, Maximum 250 items Supervised stage: Upper stage in 2 stage and lower stage in 2 stage Supervising method: Instantaneous/time limit/AND supervision Supervisory period: 0.1 sec Supervising grouping: Maximum 3 groupings (A/B/C) 		
Correlation supervision	<ul style="list-style-type: none"> Maximum registered numbers: 10 sheets Supervised stages: Upper stage in 2 stage and lower stage in 2 stage Supervising method: Instantaneous/time limit/AND supervision Supervisory period: 0.1 sec Supervising grouping: Maximum 3 groupings (A/B/C) 		
Measurements at alarm condition	<p>For high speed</p> <ul style="list-style-type: none"> Telemetry period: 10 ~ 90 ms at 10 ms pitch Measurement times after the occurrence of error: 3000 times Max. Measurement items: 20 items Max. <p>For low speed</p> <ul style="list-style-type: none"> Telemetry period: 0.1 ~ 99.9 s Measurement times after the occurrence of error: 3000 times Max. Measurement items: 20 items Max. 		
Real-time monitor editor	Basic monitor parts: analog meters, digital meters, bar graphs, Trend 1, Trend 4, pictures, labels, ramp, averaged measurement trends, auto-operation monitor, auto-operation graph monitor		
Tabulating	Type of tabulating data: Averaged measurement data, high-speed measurement data, continuous measurement data Number of tabulating items: Maximum 16 items per a line, Maximum 3 lines (Maximum 48 items per a tabulating)		
2-D graph plotting	Multiple Y-axis graph (Maximum 10 Y-axis) Comparing X-Y graph (Maximum 5 measurement data file)		
External CPU linkage	LAN, Data exchange through a common folder		
Security level	3 levels of security can be set up on user side.		

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* PowerPC is the registered trademark of IBM Corp., U.S. * MATLAB, Simulink is the registered trademark of The MATHWORKS Inc.



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